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Social coordination dynamics: Measuring human bonding

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Social coordination dynamics: Measuring human bonding

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Spontaneous social coordination has been extensively described in natural settings but so far no controlled methodological approaches have been employed that systematically advance investigations into the possible self-organized nature of bond formation and dissolution between humans. We hypothesized that, under certain contexts, spontaneous synchrony—a well-described phenomenon in biological and physical settings—could emerge spontaneously between humans as a result of information exchange. Here, a new way to quantify interpersonal interactions in real time is proposed. In a simple experimental paradigm, pairs of participants facing each other were required to actively produce actions, while provided (or not) with the vision of similar actions being performed by someone else. New indices of interpersonal coordination, inspired by the theoretical framework of coordination dynamics (based on relative phase and frequency overlap between movements of individuals forming a pair) were developed and used. Results revealed that spontaneous phase synchrony (i.e., unintentional in-phase coordinated behavior) between two people emerges as soon as they exchange visual information, even if they are not explicitly instructed to coordinate with each other. Using the same tools, we also quantified the degree to which the behavior of each individual remained influenced by the social encounter even after information exchange had been removed, apparently a kind of social memory.
INTRODUCTION

Social interactions represent a substantial portion of many daily activities in human populations. A common and well-described consequence of this interpersonal activity is that an individual’s behavior, whether intentional or not, is modified through interactions with others (Insel & Fernald, 2004). Thus, from the very first months of life, individuals live vicariously through one another, adopting spontaneously, if only temporarily, a similar posture or tempo during a conversation with a peer, or imitating their favorite singer (e.g., Bernieri, Reznick, & Rosenthal, 1988; Condon & Sandler, 1974; McGarva & Warner, 2003; Meltzoff & Decety, 2003; Peery, 1980). Alterations of the individual and collective behaviors range from imitation and mimicry to spontaneous synchronization, and have been observed in groups varying in size from dyads to thousands of individuals (e.g., Barsalou, Niedenthal, Babey, & Ruppert, 2003; Motter, Nishikawa, & Lai, 2003; Strogatz, 2003).

Synchronization is a form of spontaneous pattern formation that operates according to general principles of self-organization described by nonlinear dynamics (Haken, 1983; Nicolis & Prigogine, 1977). Although different processes can underlie synchronization (see Pikovsky, Rosenblum, & Kurths, 2001; Strogatz, 2003, for reviews), spontaneous phase synchrony has been observed among very different entities in a broad range of physical, biological and social systems ranging from Josephson junctions (Tsengyankov & Wiesenfeld, 2002) to fireflies (Winfree, 1967), sinoatrial pacemakers (Michaels, Matyas, & Jalife, 1987), columns in the visual cortex (Gray, Konig, Engel, & Singer, 1989) and firing neurons (Nunez, Panetsos, & Avendano, 2000). Following on Huygens’s analysis of two clocks synchronizing on a wall (Bennett, Schatz, Rockwood, & Wiesenfeld, 2002; Hugoni, 1673), many studies have since framed the problem of mutual synchronization in terms of a network of oscillators whose individual behavior is altered by nearest-neighbor interactions (Bottani, 1996; Kuramoto, 1984; Pikovsky et al., 2001; Strogatz, 2003; Winfree, 1967, 1980).

The coordination dynamics of human brain and behavior has proven no exception to the principles of self-organized synchronization (Fuchs, Kelso, & Haken, 1992; Kelso, 1995; Kelso et al., 1992, 1998). For instance, experiments reveal that humans exchange information (uni- or multi-sensory in nature) to spontaneously coordinate and switch behavioral patterns (e.g., Kelso, 1984; Lagarde & Kelso, 2006). A common social illustration is the clapping of an audience where sometimes applause occurs in unison, with many individuals clapping as a single synchronized ensemble (Nédé, Ravasz, Brechet, Vicsek, & Barbarasi, 2000a; Nédé, Ravasz, Vicsek, Brechet, & Barbarasi, 2000b). Mechanisms governing the phenomenon are highly context dependent, even within the same audience and depend on whether people applaud in unison with or without music. From an experimental perspective, clapping in synchrony with the beat of the music is equivalent to intentional sensorimotor coordination with an external event, such as a metronome (Kelso, 1995). Several studies have employed the sensorimotor coordination paradigm to investigate interpersonal coordination dynamics for the case when an individual intentionally synchronizes his/her movements with another by means of visual information exchange (e.g., de Rugy, Salesse, Oullier, & Temprado, 2006; Oullier, de Guzman, Jantzen, & Kelso, 2003; Schmidt, Carallo, & Turvey, 1990; Temprado, Swinnen, Carson, Tourment, & Laurent, 2003). In such studies, however, it is not yet clear whether spontaneous social entrainment actually occurs, i.e., as a two-way interaction where people mutually influence each other, or whether one individual simply acts as a pacing stimulus or “driver” for the other (Kelso, DeColle, & Schöner, 1990). A different scenario, however, is characteristic of the end of a live performance when each individual applauds according to his/her preferred pace and in the absence of driving stimuli from the stage. Nonetheless, the audience will quickly and spontaneously entrain to a common rhythm such that everyone claps in unison. Note that at this moment, an individual’s clapping behavior is influenced solely by exchange of auditory (and possibly visual) information (Nédé et al., 2000a,b).1 Individual entities communicating via a medium of information exchange constitutes a minimum requirement for self-organized coordination to emerge (Kelso, 1995; Winfree, 2002).

1 A beautiful example of the same audience clapping in synchrony at two separate moments of a live musical show is seen in the world-famous New Year’s Concert given every year by the Vienna Philharmonic Orchestra in Austria while and after the Radetzky March by Johann Strauss Jr. is played. This
In spite of an abundant literature addressing social coordination, many questions remain regarding the nature of the behavioral and neural processes mediating the formation and dissolution of bonds between individuals and how such processes may be quantified (Balaban, 2004; Konner, 2004). Three major problems exist when trying to understand spontaneous synchronization in social settings.

The first is the challenge of complexity, both in terms of the large number of units to analyze (e.g., thousands of pairs of clapping hands, cf. Néda et al., 2000b) and/or the nature of the behavior itself (e.g., mother–infant synchronization, cf. Condon & Sandler, 1974). Such compositional and behavioral complexity has hindered experimental attempts to record and quantify both the individual and social dynamics. Even the reduction in dimensional complexity afforded in coordinated behavior can only go so far in elucidating the relationship between group behavior and the individual units of which it is composed.

Second, even when the source and nature of the coupling has been identified, it is difficult to manipulate experimentally relevant variables such as the coupling intensity (e.g., Néda et al., 2000b). Almost by definition, spontaneous behavior is not externally goal directed or explicitly controlled. Most of the results reporting unintentional synchronization in humans are based on observation and categorization methods that rely primarily on the experimenter’s appreciation of a given exemplar behavior rather than a quantitative measure of coupling and individual behavior (e.g., Barsalou et al., 2003; Condon & Sandler, 1974; but see Richardson, Marsh, & Schmidt, 2005).

A third problem comes from the possibility that any change in a person’s behavior induced by interacting with another may persist even after the encounter is over. We term this remnant of a prior social interaction social memory. Social memory implies at the very least, that the intrinsic parameters of the individual components have been altered by virtue of the social interaction. Social memory is thought to play an important role in human actions, and, to a larger extent, in the way we live (Insel & Fernald, 2004). A deeper understanding of social memory may ensue if one is able to quantify the strength and persistence of prior social influences on an individual’s behavior.

In the present study, we focused on a most basic unit of social interaction: a pair of individuals interacting via visual information exchange. Focusing on the dyad constitutes a crucial first step, allowing for experimental control of information exchange and a precise quantification of the nature and strength of the social interaction. Additionally, our paradigm circumvented some of the limitations of existing work on social coordination and provided a more ecologically valid methodology. Previous work (e.g., Schmidt & O’Brien, 1997) hinted at the emergence of spontaneous motor coordination between individuals but the authors explicitly instructed each member of the dyad to try and maintain their own rhythm (i.e., resist the interpersonal influence). Here, we turned the issue around and identified instead the coordinative patterns that emerged only as a function of visual information exchange. Pairs of participants executed rhythmic movements while in full view of each other’s and their own ongoing actions without any other additional task to perform (see Sebanz, Bekkering, & Knoblich, 2006, for a review on joint actions).

We tested the hypothesis that even without instructions to do so, spontaneous synchronization between partners would occur as soon as they were coupled visually while performing the rhythmic task. Further, we explored the possibility that once the visual coupling was removed, individual movements, although no longer synchronized, might remain influenced by the social encounter after it was over, thereby implicating memory as a distinguishing feature of human self-organizing systems. Just as kinematic studies have elucidated the neural basis of motor control (see, e.g., contributions in Latash & Lestienne, 2006) the present work sets the stage and provides new methods for neurophysiological investigations of social interaction. So far the latter have tended to assess the behavioral actions of pairs...
of individuals one at a time or through imitation after some delay. In many everyday social settings, as in the present paradigm, both members of a pair adjust in an ongoing fashion to the other’s behavior in real time. Thus, the present paradigm had genuine potential to expose the neural mechanisms of real-time social coordination. A step in this direction has already begun with its replication while simultaneously recording brain activity of each member of the dyad (Tognoli, Lagarde, de Guzman, & Kelso, 2007).

MATERIALS AND METHODS

Overview

Pairs of participants, sitting in front of each other (see Figure 1A) executed rhythmic finger movements, each at their own preferred pace and amplitude and without the benefit of externally imposed pacing stimuli. A trial was partitioned equally into three time-contiguous phases during which both participants either exchanged visual information or did not. The interaction was controlled by allowing (or not) visual contact between participants, coupling being mediated by the exchange of visual information regarding the other’s actions. When visual interaction was allowed, participants observed both their own motion and the motion of the other (Figure 1B).

Participants

Six pairs of participants (8 males and 4 females, pairs were either mixed or same gender) between the ages of 22 and 55 volunteered for the experiment. All participants (graduate students at Florida Atlantic University) provided informed consent and were naive to the purpose of the study. The experiment received full approval from the IRB of Florida Atlantic University. Our hypothesis states that visual coupling may induce participants to spontaneously synchronize their movements in space and time. The observations of spontaneous adjustments in oscillation frequency necessary to achieve interpersonal synchrony required forming pairs in which participants demonstrated different initial preferred movement frequencies. To do so, the preferred frequency of each participant (movement with eyes open and fixated on a stationary object) was recorded several days prior to the experiment. Pairs were then formed using individuals who differed in intrinsic frequency.

Setting, instructions and task

Two participants sat opposite each other and grasped a plastic dowel in a pronated (palms down) position with a 30 cm separation between their hands (Figure 1). Participants were instructed to move their right index finger up and down continuously at their preferred amplitude and frequency “as if they were going to do it all day”. It was emphasized to the subjects that the trials were to be performed without interrupting ongoing movement. No external metronome was used to pace the movements to prevent possible coordination with respect to the auditory signal rather than with the other member of the dyad (cf. Schmidt et al., 1990). No specific instructions were given as to how participants should move relative to each other. In addition, participants were told not to resist if they felt/realized that their coordination with respect to the other changed over a trial. Within each trial, participants alternated eyes-open and eyes-closed segments. Participants were further instructed to look at each other’s finger (and thereby their own, Figure 1B) during eyes-open segments. To minimize distractions from the surroundings, large black panels were placed behind each participant.

Experimental conditions

Each condition lasted 1 minute and was divided into three 20 s segments. Segments were defined by the presence or absence of visual contact, which was controlled based on a set of instructions to participants to open or close their eyes. The beginning of each segment was signaled by an auditory beep. The order of presentation of visual information exchange (or the absence
thereof) was alternated across trials resulting in two experimental conditions (see Figure 1C):

1. Closed–Open–Closed (C–O–C): both participants’ eyes closed (0 to 20 s)—both participants’ eyes open (20 to 40 s)—both participants eyes closed (40 to 60 s); and

2. Open–Closed–Open (O–C–O): both participants’ eyes open (0 to 20 s)—both participants eyes closed (20 to 40 s)—both participants eyes open (40 to 60 s).

Compliance with the instruction to open or close the eyes was monitored by an experimenter hidden from the participants’ view. Both experimental conditions were executed 10 times by each pair of participants. The order of both the conditions and the trials was randomized.

Data acquisition

Finger movements were recorded on an OPTOTRAK 3010 (Northern Digital Inc., Waterloo, Ontario, Canada) 3D acquisition system using one infrared emitter (IRED) attached to the tip of the right index finger and three reference IREDS fixed to the supporting apparatus. The reference IREDS defined a vertical plane onto which the finger movements were projected. The projected angle formed by two vectors (the directed line from a reference point to the finger
and another directed line from the same reference point to another reference point) was used as the measure of finger movements. Data were sampled at 120 Hz.

**Data analysis**

In coordination dynamics, the behavior of a given system can be captured by the value of low-dimensional collective variables known as the order parameter. In the vicinity of critical points, emergent behavior is governed by the dynamics of these collective variables (e.g., Haken, 1983; Kelso, 1995). In experimental cases the order parameters are not known in advance but have to be discovered. For the situation of biological coordination an appropriate order parameter describing the system dynamics is the relative phase ($\phi$) between the elements to be coordinated (Haken, Kelso, & Bunz, 1985; Kelso, 1984).

The first quantity computed was the peak-to-peak relative phase (Kelso, 1984; Zanone & Kelso, 1992) between the index finger flexion-extension movements of participants A and B. The relative phase measure ($\phi$) allows for a dimensional reduction of the system as it captures the macroscopic spatiotemporal behavioral pattern. Hence, four degrees of freedom (position and velocity of each component) are compressed onto a single value that summarizes the organization of the (un)coupled system formed by the dyad. Quantitative evaluation of spontaneous synchrony was also provided by the Fast Fourier Transform (FFT) power spectrum overlap (PSO) between the movements of both fingers. PSO measures the percentage of movement frequencies common to both partners in a pair. Defined as the area of intersection between each participant’s normalized spectral plots, the PSO is an indicator of the strength of the frequency entrainment between the two participants (Oullier, Bardy, Stoffregen, & Bootsma, 2002). Finally, a third measure, the peak frequency, defined as the frequency at the maximum of the (movement) FFT power spectrum, was computed for each participant in each segment of a trial.

The previously described analysis and the associated linear statistics were performed with Matlab (The Mathworks, Inc, Natick, MA, USA). Circular statistics (Batschelet, 1981) applied to the relative phase data were computed with Oriana (Kovach Computing Services, Pentraeth, UK) and included Kuiper’s test to compare distributions of $\phi$-values with the uniform distribution and Watson’s $U^2$ to compare one distribution to another.

**RESULTS**

**Interpersonal coordination pattern**

Trajectory and relative phase. Evolution of the relative phase (between the movements of each individual of a pair) through the three segments of experimental trial indicates if and possibly when spontaneous synchronization emerges. Figure 2A shows the three segments of a Closed–Open–Closed (C–O–C) trial from a representative pair. The left, middle, and right columns (labeled 1, 2 and 3) plot the movement trajectories with the participants’ eyes closed, open, and closed again, respectively. When the eyes were closed (segment 1), each participant produced movements independently at his/her own frequency (Figure 2A, segment 1). Due to intrinsic frequency differences, the relative phase ($\phi$) between the participants’ finger motions exhibited phase wrapping (Figure 2C, segment 1). Phase wrapping occurs when the components oscillate independently at different frequencies. In the first segment of a C–O–C trial, phase wrapping reveals the absence of synchronization as it indicates that individual behaviors are not coordinated.

Following a simple auditory cue to open their eyes and look at each other’s finger motion (while being in full view of their own movements), participants spontaneously adopted in-phase coordination illustrated by the peak extension and flexion of movements of participants occurring (more or less) at the same time (Figure 2A, segment 2). This is also indicated by $\phi$ stabilizing at around 0° constituting a clear measure of their movements being coordinated in an in-phase fashion (Figure 2C, segment 2, yellow overlay). On a signal to close the eyes again, the frequencies diverged and $\phi$ fell back into phase wrapping (Figure 2C, segment 3) with movements of each participant no longer being in phase (Figure 2A, segment 3). Similarly, spontaneous synchronized (in-phase) patterns also emerged during segments of the Open–Closed–Open (O–C–O) condition when participants had their eyes open (Figure 2D, segments 1 and 3).
These spontaneous behaviors during the eyes-open segments were very consistent in both C-O-C and O-C-O conditions as confirmed by the distributions of relative phase-values across all the trials (C-O-C: Figure 2E; O-C-O: Figure 2F). The distributions clearly exhibit a peak value of $\phi$ around 0°, revealing the spontaneous adoption of a 1:1 synchronized coordination pattern whenever eyes were open and participants were provided with vision of each other’s movements (Figure 2, yellow overlays). Table 1 provides a statistical quantification of the distributions of $\phi$-values across all subjects in every segment of each experimental condition. In eyes-closed segments, $\phi$-values are more uniformly distributed compared to eyes-open segments, regardless of the experimental condition (C-O-C or O-C-O). Statistical analyses also revealed a substantial decrease in the stability of the interpersonal coordination pattern spontaneously adopted (illustrated by the circular variance of the relative phase) for segments where eyes are open compared to closed. In addition, in the C-O-C condition, a significant difference of relative phase distributions was found when segments 1 (eyes closed) and 2 (eyes open; Watson’s $U^2 = 6.297, p < .001$) and segments 2 (eyes open) and 3 (eyes closed; Watson’s $U^2 = 6.297, p < .001$) in the C-O-C and O-C-O conditions, respectively.

**Table 1**

<table>
<thead>
<tr>
<th>Segment</th>
<th>C-O-C condition</th>
<th>O-C-O condition</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Closed</td>
<td>Open</td>
</tr>
<tr>
<td>Circular variance</td>
<td>0.95</td>
<td>0.56</td>
</tr>
<tr>
<td>Circular standard deviation</td>
<td>142.18</td>
<td>75.53</td>
</tr>
<tr>
<td>Kuiper’s test (uniform, V)</td>
<td>2.074</td>
<td>12.108</td>
</tr>
<tr>
<td>Kuiper’s test (p)</td>
<td>&lt;.01</td>
<td>&lt;.01</td>
</tr>
</tbody>
</table>

Figure 2. Relative phase between the participants’ movements. (A–B) Displacement of the index finger of both participants during representative trials in the (A) Closed–Open–Closed C-O-C and (B) Open–Closed–Open O-C-O conditions. (C–D) Peak-to-peak relative phase $\phi$ between the movements of the index finger of the participants during C-O-C (C) and O-C-O (D). (E–F) Distribution of all the relative phase $\phi$-values in 20° bins across all pairs of participants ($n=6$) and all trials (10 per pair) during C-O-C (E) and O-C-O (F). The yellow overlays outline spontaneous synchronization.
3.891, $p < .001$) were compared. Similarly, in the O–C–O condition, comparison of distributions in segments 1 (eyes open) and 2 (eyes closed; Watson’s $U^2 = 6.787$, $p < .001$) and segments 2 (eyes closed) and 3 (eyes open; Watson’s $U^2 = 6.265$, $p < .001$) were highly significant.

Frequency overlap. We used the power spectrum overlap (PSO) to gauge the relative strength of movement coordination frequency between the two participants during the eyes-open and eyes-closed segments. The PSO was significantly higher when there was visual exchange in both C–O–C (segment 2) and O–C–O (segments 1 and 3) conditions (Figure 3; see also Table 2 for detailed statistical comparisons). The power spectrum overlap was significantly greater during eyes-open segments compared to eyes-closed segments of the same condition. No differences were found when comparing between eyes open segments of the O–C–O condition (Table 2).

Overall, relative phase and frequency overlap measures led to the same conclusion: with visual information exchange, participants tend to mutually couple at a common phase and frequency, whereas in the absence of vision of each other’s hand movements, the movement trajectories diverge and behave independently. Importantly, no participant reported having intentionally tracked the finger movements of the other during the experiment. These results enable us to conclude that the coordination was an emergent behavior spontaneously brought about by information exchange. We note again that our results

### Table 2

<table>
<thead>
<tr>
<th>Segments compared</th>
<th>Z</th>
<th>p</th>
<th>Significance level</th>
</tr>
</thead>
<tbody>
<tr>
<td>OCO_1_Open vs. OCO_2_Closed</td>
<td>2.35</td>
<td>.018</td>
<td>*</td>
</tr>
<tr>
<td>OCO_1_Open vs. OCO_3_Open</td>
<td>0.34</td>
<td>.731</td>
<td>ns</td>
</tr>
<tr>
<td>OCO_2_Closed vs. OCO_3_Open</td>
<td>2.76</td>
<td>.005</td>
<td>**</td>
</tr>
<tr>
<td>COC_1_Closed vs. COC_2_Open</td>
<td>6.29</td>
<td>.001</td>
<td>**</td>
</tr>
<tr>
<td>COC_1_Closed vs. COC_3_Closed</td>
<td>4.30</td>
<td>.001</td>
<td>**</td>
</tr>
<tr>
<td>COC_2_Open vs. COC_3_Closed</td>
<td>5.61</td>
<td>.001</td>
<td>**</td>
</tr>
<tr>
<td>OCO_2_Closed vs. COC_1_Closed</td>
<td>4.19</td>
<td>.001</td>
<td>**</td>
</tr>
<tr>
<td>OCO_2_Closed vs. COC_3_Closed</td>
<td>0.09</td>
<td>.926</td>
<td>ns</td>
</tr>
</tbody>
</table>

Notes: *$p < .05$; **$p < .01$; ns = non significant. OCO = Open-Closed-Open condition; COC = Closed-Open-Closed condition; 1, 2 or 3 = segment number within the condition; Open or Closed = Visual information exchange or not.

![Figure 3](image-url)
may be distinguished from previous dyadic studies in which one participant was explicitly instructed to track (or drive) the other (e.g., de Rugy et al., 2006; Oullier et al., 2003; Schmidt et al., 1990; Temprado et al., 2003) or to resist the mutual influence each member of the dyad exerted on the other (Schmidt & O'Brien, 1997).

**Social memory**

Our results might be considered a remarkable example of mutual entrainment between oscillators coupled through a medium of information exchange (Winfree, 2002). Such a view predicts that once the coupling is removed, each oscillator should return to its own intrinsic frequency and any influence of the interaction should disappear. The situation between two people, however, is not so generic. A closer look at the frequency distributions in the C–O–C condition revealed that participants do not revert to their initial “preferred” frequency and may carry a memory of the previous rhythm (from hereon referred to as social memory), when visual exchange is removed.

To quantify this social memory effect, we analyzed the movement frequencies for the C–O–C condition in two ways.

**Power spectrum overlap.** First, using the power spectrum overlap, we measured the similarity of movement frequency produced by the members of the dyad before and after visual contact (i.e., between segments 1 and 3 of the C–O–C condition). The logic was that if the fingers were acting as classically coupled oscillators they should revert to their respective intrinsic behaviors after severing visual contact. Empirically, therefore, the resulting PSO should be identical for the two eyes-closed time segments of the C–O–C condition. In contrast, the movement frequencies of the members of the dyad showed significantly greater overlap after spontaneous coupling (PSO = 31.3%; SD = 19.6) than before (PSO = 17.6%; SD = 15.2). A statistical comparison between the PSO from the two eyes-closed segments (1 and 3) of the C–O–C condition revealed significant differences in spite of the absence of visual exchange in both cases (Figure 3A; Table 2). Instead of returning to their preferred frequency following the removal of visual information, participants continued to be influenced by the previous coupled state.

This observation is corroborated by what happened during the second segment of the O–C–O condition (Figure 2D and 3D): the two eyes closed segments that followed eyes open ones (O–C–O segment 2 and C–O–C segment 3) revealed no significant difference in frequency overlap but significantly differed with the segment in which eyes closed did not follow visual exchange (C–O–C segment 1; see Table 2). Overall, the frequency overlap (PSO) provided a good quantitative measure of the “remnant of attraction”.

**Peak movement frequency.** Second, we tracked the peak movement frequencies as a participant traversed the three time segments of the 60 s trial. Direct comparison of the two eyes-closed segments of a C–O–C condition revealed a significant difference between pre- (segment 1) and post-coupling frequencies (segment 3), t(119) = 11.23, p < .001. After viewing each other’s finger movements, participants did not relax back to their initial frequency but adopted a new one as a result of their interaction. Effects of visually induced social coupling were also clear in the sequence of relative phase plots, where the moderating effect of the coupled phase-locking state on the previous phase wrapping behavior was expressed by a reduction of the slope of \( \phi \) (compare segments 1 and 3 of Figure 2C) and the concentration values of the relative phase and its circular variance in each segment (cf. Table 1).

To investigate how long this remnant endures, we ran a simple ancillary experiment that systematically increased the length of the third segment of the C–O–C trial. Whether the third segment lasted 20, 30 or 60 s, similar results were observed: participants did not relax back to their initial movement frequency as long as finger oscillations were executed. Moreover, participants consistently started the new trial moving at their previously determined preferred frequency. Hence, the social memory effect observed in the C–O–C trials appeared to disappear once the participants stopped moving or when a new trial began.

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3Although interesting, the latter result should be considered with caution since it reports a comparison between two eyes-closed segments from two different conditions.
Dependence on initial conditions

Based on initial frequency screening, participants could readily be identified as having the higher (H) or lower (L) preferred frequency of the pair. Sorting participants with respect to this criterion revealed an unexpected directionality effect that provided greater insight into how initial conditions, in this case initial preferred frequency (L or H), in part determines how the individual movement frequencies evolve throughout the trial. In 86.6% of trials, the participant with the lowest initial frequency of movement (L) increased his/her frequency when switching from eyes closed to eyes open (from segment 1 to segment 2; Figure 4C) whereas the one with the higher initial frequency (H) decreased in 75% of the cases, $\chi^2 = 109.10, p < .01$ (Figure 4D). When closing their eyes again (from segment 2 to 3), L participants slowed down toward their initial “intrinsic” frequency (83.3% of the cases) and H participants also slowed down away from their own intrinsic frequency when vision was removed (75%; $\chi^2 = 34.10, p < .01$).

During the C–O–C condition, there was therefore a different directionality effect in peak frequency change depending on whether a given member of the dyad initially had a higher (or lower) preferred frequency. Shifts in frequency observed across segments 1 and 3 of a C–O–C trial, resulted from the L participant increasing frequency (78.3% of the cases) and the H participant decreasing frequency (93.3%), as confirmed by a $\chi^2$ test ($\chi^2 = 137.08, p < .01$). These results were confirmed by computation of the average frequency for each participant (L and H) in each segment of the C–O–C condition (Figure 4C and D). Importantly, participants starting the trial with the higher initial movement frequency (H) were more affected by the interaction, as the difference between their initial and final frequencies was significantly higher.

Figure 4. Directionality effect in peak frequency changes in the C–O–C condition. Power spectrum of the movement of the participant with (A) the lowest (L) initial preferred frequency (red) and (B) the highest (H) initial preferred frequency (blue) for each of the three time segments. For both participants, the effects of opening and closing the eyes is illustrated by green and black arrows respectively. (C–D) Grand average of the peak frequencies for each kind of participant (L and H) in each time segment. T-test significance: *$p < .05$; **$p < .01$. 

spontaneous synchronization
more, 2003). Interestingly, such interference is of a similar action (Kilner, Paulignan, & Blake-Stoffregen, 1985). In addition, experimental data show that the mere observation of the movements of another person interferes with one’s execution of a similar action (Lee & Lishman, 1975; Oullier et al., 2002; experiments using a moving-room paradigm (e.g., oscillating in their environment as illustrated by social coordination? Human movements can be change might have facilitated such spontaneous encounters. A notable feature of this framework is its ability to uncover generic mechanisms common to different kinds of systems at different levels of observation. For instance, the same basic patterns of coordinated behavior and pattern dynamics (multistability, critical fluctuations accompanied by a temporary loss of stability, phase transitions, hysteresis and critical slowing down) have been observed within an individual in studies of bimanual and single limb movement coordination, studies of sensorimotor coordination between an individual and the environment or between individuals (see Jantzen & Kelso, 2007; Kelso, 1995; Swinnen, 2002, for reviews). Here we investigated how the natural (uninstructed) social influence of one person on another evolves in real time and we report two key findings. The first is that humans immediately and spontaneously coordinate their actions with each other when provided with vision of the movements of the other’s hand together with their own. The second is that an individual’s intrinsic behavior is altered by the social interaction: that is, the effect of the previous social encounter persists when vision of the other’s movements is no longer available. Dynamical measures such as relative phase and power spectral overlap proved to be adequate quantifications of the spontaneous coupling between individuals, the transition to loss of entrainment and the persistence or “social memory” of the encounter.

What features of the visual information exchange might have facilitated such spontaneous social coordination? Human movements can be affected unintentionally by the vision of an object oscillating in their environment as illustrated by experiments using a moving-room paradigm (e.g., Lee & Lishman, 1975; Oullier et al., 2002; Stoffregen, 1985). In addition, experimental data show that the mere observation of the movements of another person interferes with one’s execution of a similar action (Kilner, Paulignan, & Blakemore, 2003). Interestingly, such interference is less noticeable when the movement being observed is generated by human-figured robots (see also Castiello, 2003). Recent work in our laboratory has examined the degree of coordination that occurs when a single individual performs the present task in front of a computer-generated hand that moves along a sinusoidal or a pre-recorded realistic trajectory (de Guzman, Tognoli, Lagarde, Jantzen, & Kelso, 2005). Spontaneous synchronization was most likely when participants moved while viewing the computer-generated hand driven by a realistic trajectory. However, unlike the present results, synchronization was not observed in 100% of the trials and, when present, was supported by a significantly lower frequency overlap (de Guzman et al., 2005). One may invoke a one-way coupling to explain these latter findings, since—unlike the present work—the motion of the computer-generated hand could not be influenced by the movement of the participant.

Taken together, the foregoing results suggest that biological relevance, and biological motion in particular, play a key role in the formation of social coupling. One explanation of our findings may be found at the neurophysiological level. For instance, some areas of the brain are known to be associated with the perception (but not the execution) of biological motion including the posterior superior temporal sulcus or STS (Allison, Puce, & McCarthy, 2000; Grèzes, Armony, Rowe, & Passingham, 2003; Grèzes et al., 2001; Iacoboni et al., 2005). STS is also known to be a source of afferent input for the so-called human “mirror system” (Rizzolatti & Craighero, 2004). Originally identified in monkeys, mirror neurons are discharging both when one performs a given action and when one sees the same action performed by someone else (Gallese, Fadiga, Fogassi, & Rizolatti, 1996). They have been located primarily in the ventral premotor cortex and the rostral region of the inferior parietal lobule (Rizzolatti & Craighero, 2004). The human mirror system constitutes a neural mechanism allowing matching between visual perception and the execution of a given action (Rizzolatti, Fogassi, & Gallese, 2001) and may also provide a basis for understanding the intentions of others (Iacoboni et al., 2005). Since participants in our experiment were both producing and observing rhythmic coordination, it seems possible that the human mirror neuron system at least partially underlies the spontaneous coordination observed. This hypothesis is supported by the conclusions of a
study that replicated our C–O–C condition while brain activity of each member of the dyad was recorded using a dual-EEG system (Tognoli et al., 2007). These authors identified a cortical rhythm that distinguished synchronized and unsynchronized interpersonal coordination whose topography was consistent with neuro-anatomical sources within the human mirror system. In addition, other neural systems are likely to be required for our task to be performed. Among them is the cerebellum, which has been reported to play a key role in perceiving (Leube et al., 2003) and timing one’s movements (Ivry & Spencer, 2004; Jantzen, Oullier, Marshall, Steinberg, & Kelso, 2007).

A serendipitous finding in our study was the consistent and persistent influence of social interaction on subsequent rhythmic behavior despite the lack of information exchange between the pair. Such a finding suggests that the connectivity and dynamics of the network engaged in the generation of spontaneous rhythmic movement is modified by social interaction, and that this new organization is retained after the completion of the social visual exchange. Recent evidence in support of this hypothesis suggests that two people engaging in a common task share a representation of each other’s movement dynamics, including trajectory amplitude and frequency (Bosbach, Cole, Prinz, & Knoblich, 2005; Decety & Sommerville, 2003; Sebanz, Knoblich, & Prinz, 2005; see also Saxe, Jamal, & Powell, 2006). Dual-EEG measurement of people involved in a joint task revealed that a stimulus referring to someone else’s action elicited a similar electrophysiological response located in frontal sites as a stimulus referring to one’s own action (Sebanz, Knoblich, Prinz, & Wascher, 2006). Sebanz and colleagues (2006) therefore provided evidence that individuals acting in a social context might form shared neurophysiological action representations. To some extent, such a (shared) representation may persist in working memory when vision is removed, i.e., when information exchange is no longer possible (Goldman, Levine, Major, Tank, & Seung, 2003; Seung & Chapman, 2003; Seung, Lee, Reis, & Tank, 2000). This notion is bolstered by evidence showing that observation of another person performing rhythmic movements generates a kinematically specific memory trace of the observed motions in primary motor cortex (Stefan et al., 2005). Moreover, representations at the neural level have been shown to be highly flexible and context dependent (Jantzen, Steinberg, & Kelso, 2004, 2005), influenced both by environmental (Wheeler, Peterson, & Buckner, 2000) and task demands (Oullier, Jantzen, Steinberg, & Kelso, 2005).

Clearly, the extent and duration of the carry-over or remnant effects found here may reflect many factors, including the strength of the bond that is formed between people, their place in the social hierarchy, the willingness of each participant to cooperate, gender differences, personality characteristics and the significance each participant attaches to the social encounter (Insel & Fernald, 2004). Our result showing that the initial conditions (who starts with the higher or lower preferred movement frequency) determine behavior after the social encounter is over hints that such issues may be precisely quantified in well-defined experimental situations such as those afforded by the present paradigm.

In conclusion, one may well ask why this kind of spontaneous interpersonal coordination occurs in the first place? Compelling examples stretching from human evolution through religious ritual and sports to political, war and economical strategy suggest that keeping together in time is one of the most powerful ways to create and sustain communities and communication (McNeill, 1995). Moreover, not moving in synchrony may be too costly for the dyad (see, e.g., Körding Fukunaga, Howard, Ingram, & Wolpert, 2004). Coordination dynamics serve as a natural framework for studying social and biological coordination in real time (Kelso & Engström, 2006). Although observational methods have elucidated various forms of social behavior (Condon & Sandler, 1974; Meltzoff & Decety, 2003), the present study offers a novel perspective and new metrics to explore systematically a fundamental form of human bonding (or lack thereof), and the self-organizing processes that underlie its persistence and change. In this respect it complements recent developments in several fields such as social cognitive neuroscience (e.g., Singer, Frith, & Wolpert, 2003; Sommerville & Decety, 2006). In addition, behavioral economics and game theory (e.g., Camerer, 1999, 2003; Sally, 2003), socioeconomics (e.g., Vinkovic & Kirman, 2006) and neuroeconomics (e.g., Camerer, Lowenstein, & Prelec, 2005; Oullier & Kelso, 2006; Zak, 2004) could also benefit from this paradigm as decision making is often studied in a disembodied fashion, i.e., with little consideration for the
role played by the “bodily dimension of attraction–repulsion” in the way people decide to behave with respect to others.

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